

Solution for metal dust falling

CP-GRIP

- Adhere the metal chip & dust that is generated by fastening
  - Prevent falling of metal chip & dust
- Reduce the friction with workpiece by coating applied
  - Reduce the torque to form female thread and realize fastening by low torque
  - Proper tightening torque is stable even when the pilot hole is unstable
  - Prevent adhesive phenomenon with workpiece

Solution for metal dust falling

The oil based viscous liquid which is enclosed in a microcapsule is applied on the screw point. (Self-tapping screw, Machine screw, Bolt, etc) We term these applied screws "CP-GRIP".



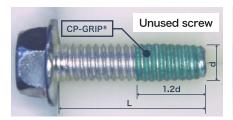
#### Self-tapping to the circuit board

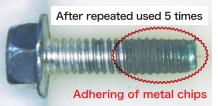
Self-tapping had been thought unfit to the circuit board due to a problem of metal chips but it can be realized. It will contribute total cost reduction, weight saving and thinning.

REPORT 01

## Prevent falling of metal chip & dust

- Testing machine Torque test machine AX-500 (Manufactured by Nitto Seiko Co., Ltd.) Rotation speed 300rpm Thrust 70.5N
- Fastening condition
- Workpiece material
- Screw: TT2000 φ6x20





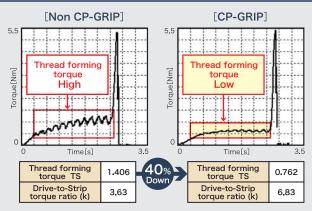


TECHNICAL 02

## Reduction of friction resistance

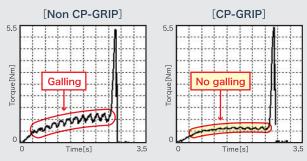
- Testing machine Torque test machine AX-200 (Manufactured by Nitto Seiko Co., Ltd.) Rotation speed 300rpm
- Fastening condition
- Workpiece material ADC12 Pilot hole diameter  $\phi$ 3.68 Drilled hole
- Screw : TAPTITE series  $\phi 4$

## Comparison of thread forming torque



\*Drive-to-Strip torque ratio (k)--- k = Stripping torque Min. / Thread forming torque Max.

#### Comparison of performance of preventing adhesive phenomenon



When the waveform amplitude grow bigger, the galling tend to be higher.

TECHNICAL 03

## Adaptivity against unstable pilot hole diameter

- Testing machine Torque test machine AX-50 (Manufactured by Nitto Seiko Co., Ltd.) Rotation speed 300rpm Thrust 69.0N
- Fastening condition
- Workpiece material ADC12
- Fastening object material:
- Automotive parts
  Screw : ALUMITITE φ2x8

Without CP-GRIP	Pilot hole dia	Proper tightening torque	Drive-to-Strip torque ratio (k)
	φ1.77	0.27~0.38N·m	3.28
	φ1.79	0.31~0.37N·m	2.76
	φ1.81	0.29~0.37N·m	3.05
	φ1.83	0.27~0.37N·m	3.22
	φ1.85	0.21~0.36N·m	4.00

	With CP-GRIP	Pilot hole dia	Proper tightening torque	Drive-to-Strip torque ratio (k)
		φ1.77	0.23~0.40N·m	4.13
		φ1.79	0.21~0.38N·m	4.21
		φ1.81	0.18~0.39N·m	5.00
		φ1.83	0.21~0.39N·m	4.29
		φ1.85	0.21~0.39N·m	4.29

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