

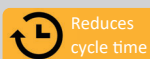
NITOMAN[®] SR580Yθ-Z

Successor to SR565Yθ-Z



Applicable
screw size
Nominal diameter
2~5mm

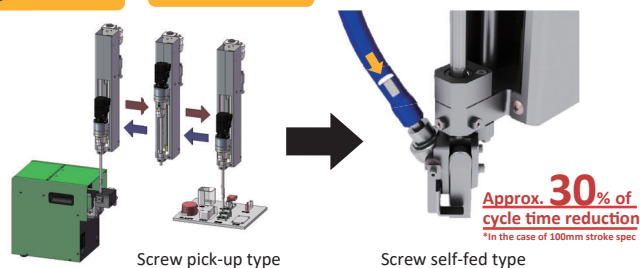
Changing manufacturing with Turnkey Screw-Driving System



Reduces
cycle time



Space-saving

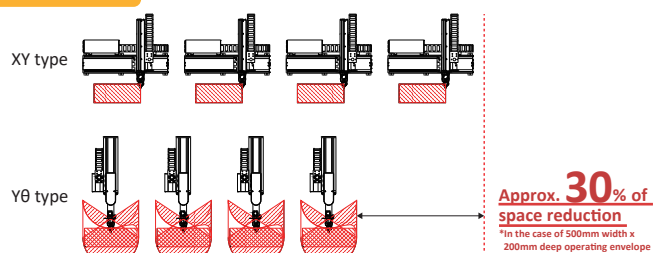


Screw self-fed type

Cycle time for self-fed type is shorter than for pick-up type. Flexibility of feeder placement helps with space constraints.

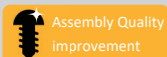


Space-saving

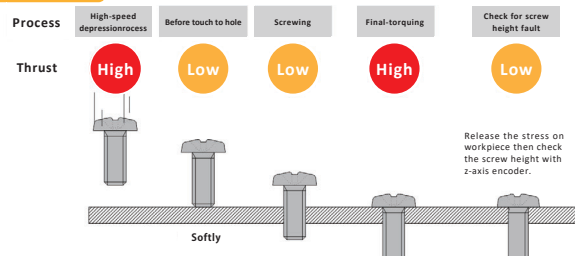


Yθ(Linear Motion + Swivel Movement) Type

Requires less space than cartesian robots thus reducing length of assembly line.



Assembly Quality
Improvement



Variable Thrust Force Control

Allows for accurate and precise setting of thrust and travelling speed of screw-driving tool. Optimum thrust control effectively prevents damage to internal threads and cam-out.



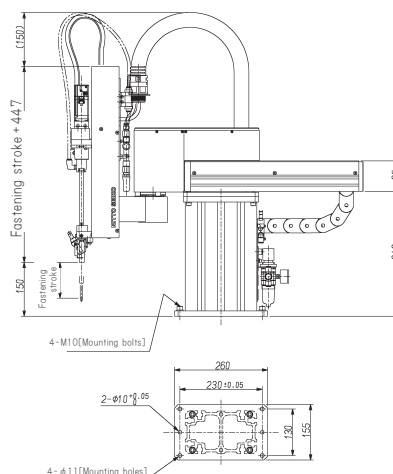
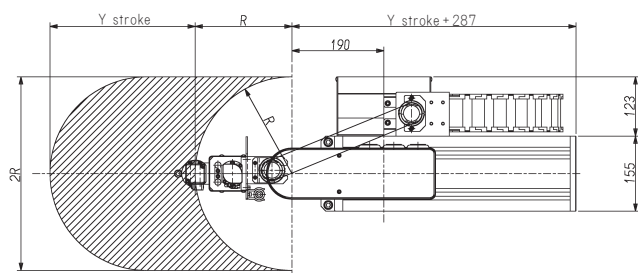
Improved
maintainability



Unified control of robot and screw driver

One controller for both robot and screw driver. Allows for easy setting and maintenance. Ability to view Torque waveform and change screw-driving parameters through teach pendant. (Optional)

Outside dimensions (: mm)



Click here for functions
of on-board driver



Reduces cycle time

Arch motion

Reduces cycle time by Arch-motion when robot returns to the ready position.

Approx. 1.6 sec cycle time reduction per 10 points.

*Excludes screw-feeding and tightening time

Assembly Quality improvement

2-Stage motion

2-Stage motion avoids interference between screw guide and workpiece for products with steps or obstructions.

Applicable for a variety of products

	SR565Y0-Z	SR580Y0-Z
Configurable points	100 models x 40 points	100 models x 100 points
	5 types	20 types

Increased configurable tightening positions and screw-driving parameters.

Ideal for applications with various products and numerous screw-driving positions.

Error analysis

Ability to save error history in CSV format

With former system, ability to see error history only available on teach pendant; however with new system, error history can be saved in CSV format.

Improved maintainability

Encoder batteries are eliminated

No need to change encoder batteries. Reduces maintenance costs and time.

Specifications of robot

Inside of [] is the option.

Type			SR580Y0	SR580Y0-Z
Screw driving unit	Number of axis to be controlled		Tow axes, simultaneously	Three axes, simultaneously
	Fastening torque control function		—	○
	Applicable Screws *1 *2	Nom Dia.	Machine screw, Tapping screw 2~5mm(except M5 truss head screws)	
		Length	max. 18mm [25], min. Screw head Dia.×1.1mm	
	Tightening torque *3		0.3~3.0N·m	
	Method of supplying screw		Blow feed or Picking up	
	Driver		KX driver, [NX driver]	
	Tightening stroke		100, [150] mm	
	Screw holding system		Vacuum tube suction system	
Fault detections	Torque fault (screw stripping), Low screw (In screw feeder)			
	Screw height fault (Micro Photo Sensor)		Screw height fault (Z-axis encoder pulse)	
Robot	Work envelope	Y-axis	200, 300, 400, 500mm	
		Turning radius	200, 250, 300mm	
		θ-axis	180°	
	Maximum moving speed	Y-axis	1000mm/sec.	
		θ-axis	360° /sec.	
		Z-axis	—	720mm/sec.
	Locating accuracy		±0.05mm	
Air pressure			0.4~0.5MPa	
Machine weight *4			Approximately 36kg	Approximately 37kg
Screw feeder			FF503H	

- *1 Products will be built up based on specification of screws, therefore it can be used for one kind of screws only.
- *2 Application range of screws will be changed by type of screw head, or size. Please contact us to make sure for it.
- *3 The type of driver varies depending on target torque.
- *4 Weight will be changed by stroke, or type of driver. Please contact us to make sure for it.

Specifications of robot controller

Inside of [] is the option.

Type	RC7000-S
Supply voltage	Single phase AC200 ~ 230V 50/60Hz
Number of axis to be controlled	Six axes, max
Robot movement	PTP, linear interpolation, circular interpolation (Interpolation operation is not supported by Y0 type robot)
Position feedback	Absolute encoder method (batteryless)
Ethernet port	8-port HUB Inside (3 ports of which are located on the front panel)
Memory	SRAM : (Battery backup: approximately five years)
External input *5 *6	Standard user port 16points [I/O expansion possible *7]
External output *5 *6	Standard user port 16points [I/O expansion possible *7]
Field network	Option *8
Teaching method	MDI, Remote teaching, Direct teaching
Point control	Work area : 100 points x 100 types Fixed area : 40 points
Program memory capacity	15MB
Robot program	Special motion language
Outside dimensions (W×H×D)	250×450×470mm
Weight	Approximately 20kg
Teaching pendant	Handy Type touch panel (with Key switch, Emergency switch and Dead-man's switch) Pendant can be used as manual control panel
PC software	[CPMC-MPE780D] *9

- *5 External I/O might be used to system programming, which depend on some device specification.
- *6 PNP type also available. (Need to specify at order timing. NPN or PNP.)
- *7 NPN: Maximum number of additional I/O points 64 input points, 64 output points
PNP: Maximum number of additional I/O points 32 input points, 32 output points
- *8 Ethernet, EtherNet/IP, EtherCAT, PROFINET, Modbus-TCP, CC-Link IE Field, FL-net, CC-Link, DeviceNet, PROFIBUS
- *9 CPMC-MPE780D is a software provided by YASKAWA Electric Corporation.

NITTOSEIKO CO.,LTD.

Assembly Machine Division

Global Sales Section

URL : <https://www.nittoseiko.co.jp/en.html>


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